

Note: H101 model files are backwards compatible with other Silverware quads, just the 3D throttle stuff needs to be disabled/ignored

DEVO 7e

H8 mini

[Model file](#) for H8mini dual mode firmware posted by syvic

[Model file](#) for H8mini dual mode firmware posted by WardoMon

H101

[Model file](#) for H101 dual mode firmware with 3D throttle enabled posted by SirDomsen

[Another one](#) with 3D throttle, posted by HappyHarry

for inverted controls like on a CP-Heli comment in

```
//#define NATIVE_INVERTED_MODE
```

Devo 7e with Switchmod

Devo 7E model file with switchable stagility/rattitude mode by RCGroups user Markus Gritsch

He got inspired by Mike Meyer and added stagility/rattitude/horizon mode to his Devo 7E model file. It requires a modded Devo 7E with two additional 3x switches.

HOLD:

0: normal

1: sticky throttle hold (see

<http://www.deviotiontx.com/forum/how-to/1953-how-to-create-a-sticky-throttle-hold> for more info)

SWA:

0: linear positive throttle over the full stick range

1: positive throttle only in the upper stick range half

2: inverted throttle in the lower stick half, normal throttle in the upper stick half – CP heli trainer

SWB:

0: level/angle mode, linear roll and pitch

1: stagility/rattitude/horizon mode (change threshold on Ch10, Page 2)

2: rate/acro mode, expo on the roll and pitch channels

FMOD:

0: low rates

1: high rates

Throttle trim buttons are used to turn the LEDs on/off

[H101/H8mini model file & config.h](#)

DEVO 7 with Goebish's NRF24_multipro

[link to Goebish's Code](#)

Inverted Flight like a CP-heli!!

[Download DEVO7 model file](#)

You have to assign the Channels in Bayang.ino (multimodule Arduino-Sketch) to be as follows:

```
packet[2] = GET_FLAG(AUX3, BAYANG_FLAG_FLIP)           //Assignment for
Devo7 + Silverware
                | GET_FLAG(AUX2, BAYANG_FLAG_HEADLESS)
                | GET_FLAG(AUX1, BAYANG_FLAG_RTH)
                | GET_FLAG(AUX6, BAYANG_FLAG_SNAPSHOT) //Not assigned in
available in DEVO 7
                | GET_FLAG(AUX5, BAYANG_FLAG_VIDEO);
packet[3] = GET_FLAG(AUX4, BAYANG_FLAG_INVERT)
```

H101 has to be configured as described [here](#)

DEVO 10

[H101 model file](#) for using H101 as a CP-Heli Trainer posted by SirDomsen

Hints for DIY model files

watch the [config.h](#) section

H8 icons for Devo

[rcgroups](#)

From:

<http://sirdomsen.diskstation.me/dokuwiki/> - **Silverware Wiki**

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