My Quad yaws and or banks near full throttle! Is that normal? What to do against that?

The issue with many different motors made by different companies, and sometimes, the ccw and cw motors are a bit different, and can cause this.

First of all, let's explain why Silverware often has "problems" near full throttle. Silverware allows full power available from the motors (with stock settings), there is no space for corrections with stock settings - but if all your motors and props are perfect, you are in control the quad and have no issues.

BUT if not, you get the mentioned problems.

Another way would be to change the pid limits to make yaw have higher priority. In file pid.c:

Quote:

How to solve that? Here is a text, freely copied from a RCGroups Post by Silverxxx